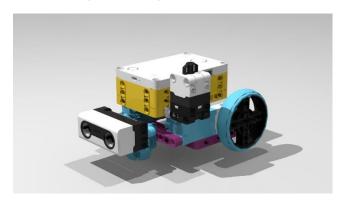
Infinite Loop Distance Sensor Bot By Wesley John Smith



Step 1: Build the Infinite Loop Distance Sensor Bot with the building instructions provided.

Step 2: Create a basic code to test if the bot is working.

```
set movement speed to 50 %

set movement motors to C+D 

set 1 motor rotation to 17.5 cm 

moved

set 1 motor rotation to 17.5 cm 

moved

torever

torever
```

Do experiments: Have learners place multiply bots on a presentation table with an edge around it or an enclosed area on the floor. How long until the first accident?

Extensions: Have the learners change the code to make it more efficient. What additions can the learners add to the bot to make it better balanced, look better, more secure in case of accidents?